

Mechanika III - 8.12.18

Metody perturbacyjne

$$x = x_0 + \varepsilon x_1 + \boxed{\varepsilon^2 x_2 + O(\varepsilon^3)}$$

$$x = x_0 + \varepsilon x_1 + O(\varepsilon^2)$$

$$x = x_0 + \varepsilon x_1$$

$$\ddot{x} + \omega_0^2 x + \varepsilon x^3 = 0$$

$$\varepsilon^0: \ddot{x}_0 + \omega_0^2 x_0 = 0 \longrightarrow x_0 = a \cdot \sin \omega_0 t$$

$$\varepsilon^1: \ddot{x}_1 + \omega_0^2 x_1 + \varepsilon x_0^3 = 0$$

$$= -\varepsilon a^3 \sin^3 \omega_0 t =$$

$$\varepsilon^1: \ddot{x}_1 + \omega_0^2 x_1 = -\varepsilon a^3 \left(\frac{3}{4} \sin \omega_0 t - \frac{1}{4} \sin 3\omega_0 t \right)$$

Metoda Galerkin

$$\mathcal{L}(x) = \ddot{x} + \omega_0^2 x + \varepsilon x^3$$

x - rozwiązanie dokładne

 \tilde{x} - rozwiązanie przybliżone

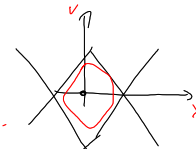
$$\mathcal{L}(x) = 0 \rightsquigarrow$$

$$\mathcal{L}(\tilde{x}) = 0$$

$$x = \sum_{i=1}^{+\infty} a_i \sin \omega_i t$$

$$x = \sum_{i=1}^{+\infty} a_i \sin c_i t$$

$$\tilde{x} = \sum_{i=1}^N \tilde{a}_i \sin c_i t$$



$$L(\tilde{x}) - L(x) \rightarrow \begin{array}{c} L(\tilde{x}) \\ \uparrow \\ \text{[Graph of } L(\tilde{x}) \text{ vs } t \text{]} \\ \downarrow \\ t \end{array}$$

$$\min \int_{(T)} (L(\tilde{x}) - L(x))^2 dt$$

$$f_{av} = \frac{\int_0^T f(t) dt}{T}$$

$$T = \int_{(T)} L(\tilde{x})^2 dt$$

min T

$$\text{dla } j=1, \dots, N \quad 0 = \frac{\partial T}{\partial a_j} = \frac{\partial}{\partial a_j} \int_{(T)} \left[L \left(\sum_{i=1}^N a_i \sin c_i t \right) \right]^2 dt$$

$$\frac{\partial}{\partial a_j} \left(L \left(\sum_{i=1}^N a_i \sin c_i t \right) \right)^2 =$$

$$= 2 \cdot L \left(\sum_{i=1}^N a_i \sin c_i t \right) \cdot \frac{\partial}{\partial a_j} \left(\sum_{i=1}^N a_i \sin c_i t \right) =$$

$$= 2 \cdot L(\tilde{x}) \cdot \sin c_j t$$

$$\text{dla } j=1, \dots, N \quad \int_{(T)} 2L(\tilde{x}) \cdot \sin c_j t dt = 0$$

$$\int_{(T)} L(\tilde{x}) \cdot \sin c_j t dt = 0$$

Ostatecznie

$$\text{dla } j=1, \dots, N \quad \int_{(T)} L \left(\sum_{i=1}^N a_i \sin c_i t \right) \cdot \sin c_j t dt = 0$$

Drgania wymuszone układu nieliniowego

$$\ddot{x} + \omega_0^2 x + \varepsilon x^3 = f \sin \omega t$$

$$\mathcal{L}(x) = \ddot{x} + \omega_0^2 x + \varepsilon x^3 = f \sin \omega t$$

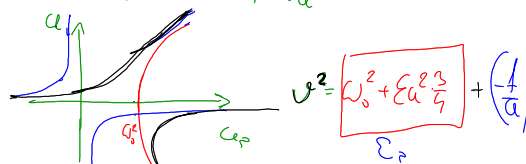
$$x = a \sin \omega t$$

$$\int_{(T)} (-a\omega^2 \sin \omega t + \omega_0^2 a \sin \omega t + \varepsilon a^3 (\sin \omega t)^3 - f \sin \omega t) \sin \omega t dt = 0$$

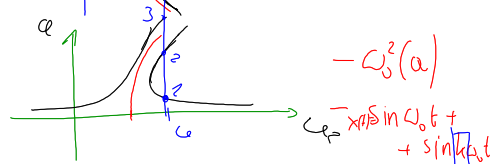
$$\int_{(T)} (\omega_0^2 a - a\omega^2 + \varepsilon a^3 \frac{3}{4} - f) \sin^2 \omega t dt + \int_{(T)} (\dots) \sin \omega t \sin \omega t dt = 0$$

$$\omega_0^2 a - a\omega^2 + \varepsilon a^3 \frac{3}{4} - f = 0 / a$$

$$\omega_0^2 - \omega^2 + \varepsilon a^2 \frac{3}{4} - \frac{f}{a} = 0$$



$$\omega^2 = \omega_0^2 + \varepsilon a^2 \frac{3}{4} + \left(\frac{f}{a} \right)$$



- $\omega_0^2(a)$
- $X_4(t)$ sąs są równoważne
- istnienie wielu rozwiązań